

http://www.youtube.com/watch?v=LcPWEMwGJVQ

Adversarial Search

CS311 David Kauchak Spring 2013

Some material borrowed from : Sara Owsley Sood and others

Admin

- Reading/book?
- Assignment 2
 - On the web page
 - 3 parts
 - Anyone looking for a partner?
 - Get started!
- Written assignments
 - Make sure to look at them asap!
 - Post next written assignment soon

A quick review of search

Rational thinking via search – determine a plan of actions by searching from starting state to goal state

Uninformed search vs. informed search

- what's the difference?
- what are the techniques we've seen?
- pluses and minuses?

Heuristic design

- admissible?
- dominant?

Why should we study games?

Clear success criteria

Important historically for AI

Fun 😊

Good application of search

hard problems (chess 35¹⁰⁰ nodes in search tree, 10⁴⁰ legal

Some real-world problems fit this model

- game theory (economics)multi-agent problems

Types of games

What are some of the games you've played?

Types of games: game properties

single-player vs. 2-player vs. multiplayer

Fully observable (perfect information) vs. partially observable

Discrete vs. continuous

real-time vs. turn-based

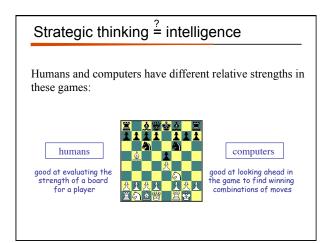
deterministic vs. non-deterministic (chance)

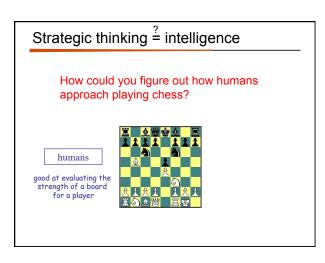
Strategic thinking [?] intelligence

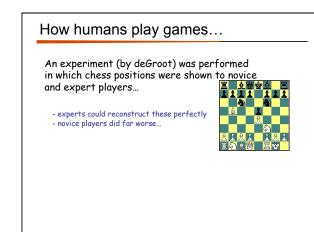
For reasons previously stated, two-player games have been a focus of AI since its inception...

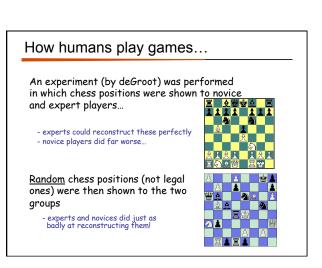


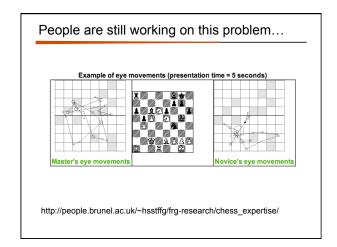
Begs the question: Is strategic thinking the same as intelligence?

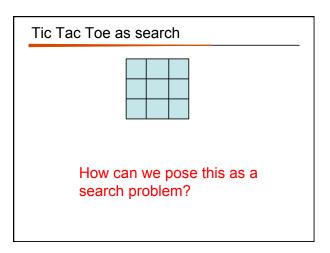


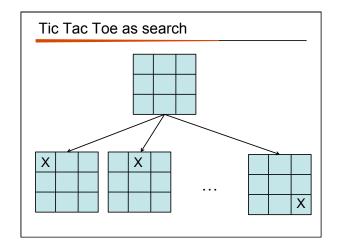


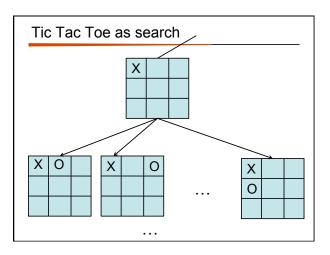


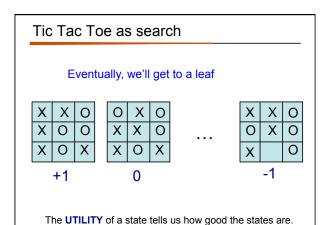












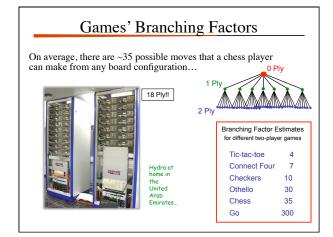
Defining the problem

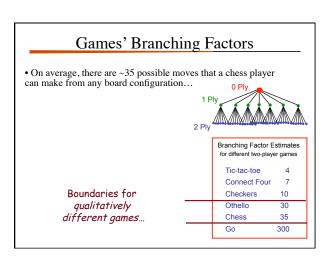
INITIAL STATE – board position and the player whose turn it is

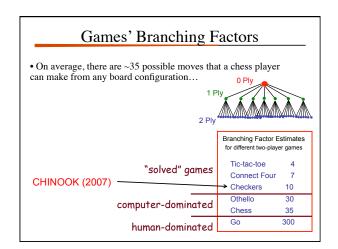
SUCCESSOR FUNCTION- returns a list of (move, next state) pairs

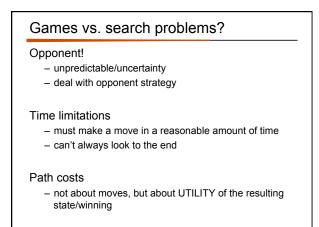
TERMINAL TEST – is game over? Are we in a terminal state?

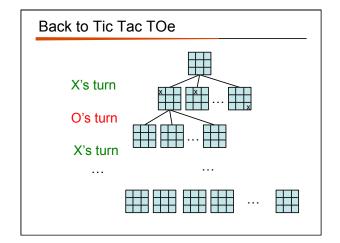
UTILITY FUNCTION – (objective or payoff func) gives a numeric value for terminal states (ie – chess – win/lose/draw +1/-1/0, backgammon +192 to -192)

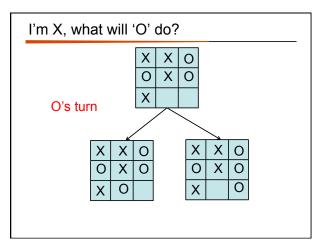












Minimizing risk

The computer doesn't know what move O (the opponent) will make

It can assume, though, that it will try and make the best move possible

Even if O actually makes a different move, we're no worse off



Optimal Strategy

An Optimal Strategy is one that is at least as good as any other, no matter what the opponent does

- If there's a way to force the win, it will
- Will only lose if there's no other option

How can X play optimally?

How can X play optimally? Start from the leaves and propagate the utility up: - if X's turn, pick the move that maximizes the utility - if O's turn, pick the move that minimizes the utility Is this optimal?

Minimax Algorithm: An Optimal Strategy

minimax(state) =

- if state is a terminal state

Utility(state)

- if MAX's turn

return the maximum of minimax(...)

on all successors of current state

- if MIN's turn

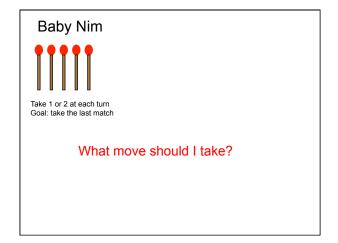
return the minimum of minimax(...)

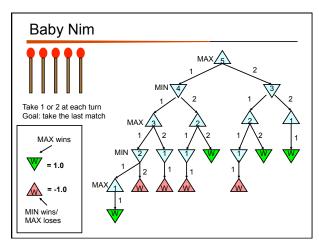
on all successors to current state

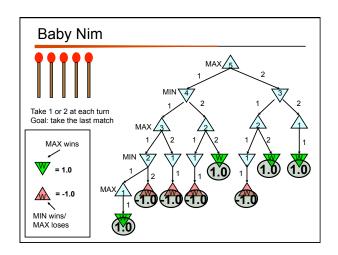
- Uses recursion to compute the "value" of each state
- Proceeds to the leaves, then the values are "backed up" through the tree as the recursion unwinds
- · What type of search is this?
- What does this assume about how MIN will play? What if this isn't true?

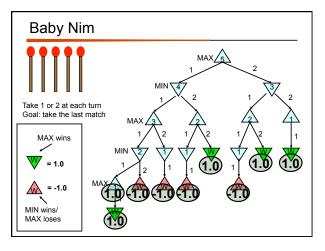
def minimax(state): for all actions a in actions(state): return the a with the largest minValue(result(state,a)) def maxValue(state): if state is terminal: Assume the return utility(state) opponent will try and # return the a with the largest minValue(result(state,a)) minimize value, for all actions a in actions(state):
value = max(value, minValue(result(state,a)) maximize my move return value def minValue(state): OPPONENT: if state is terminal: return utility(state) Assume I will try and maximize my # return the a with the smallest maxValue(result(state,a)) value, minimize his/ for all actions a in actions(state): value = min(value, maxValue(result(state,a)) her move

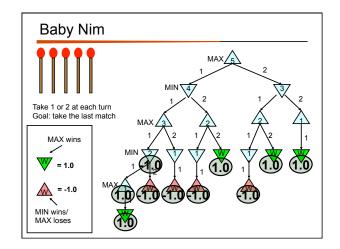
return value

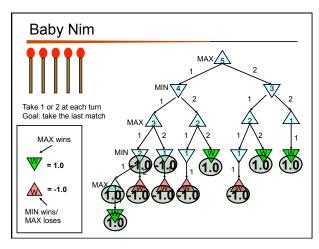


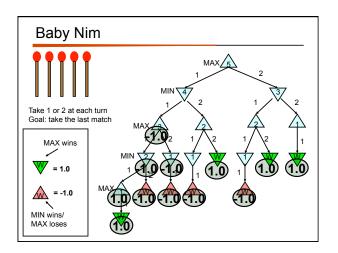


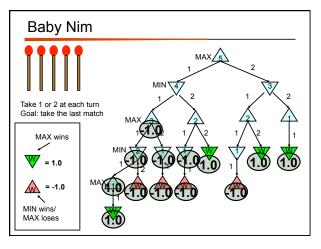


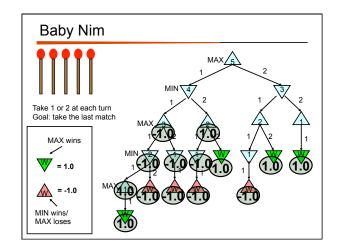


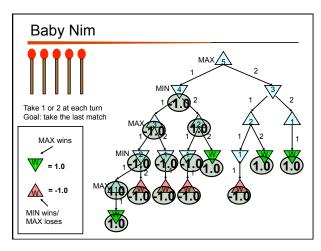


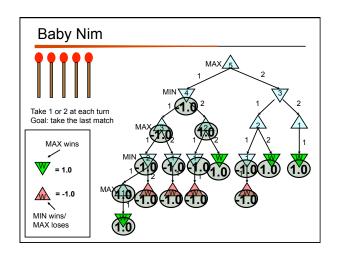


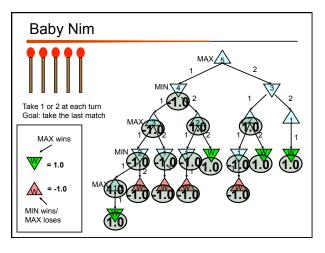


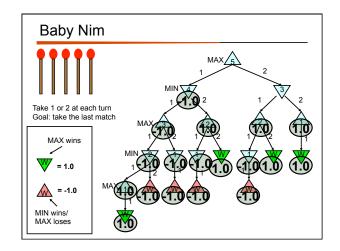


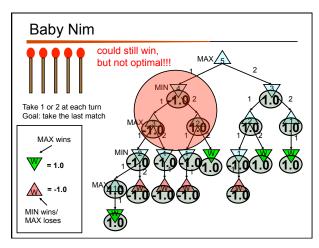


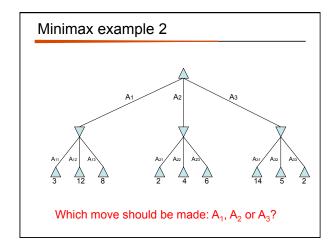


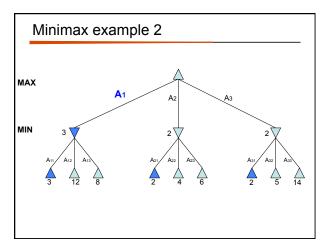












Properties of minimax

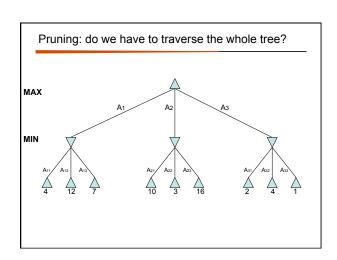
Minimax is optimal!

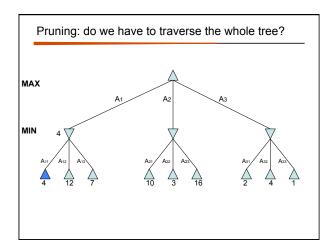
Are we done?

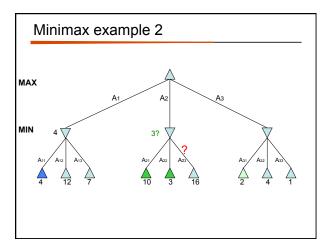
- For chess, b ≈ 35, d ≈100 for reasonable games → exact solution completely infeasible
- Is minimax feasible for Mancala or Tic Tac Toe?
 - Mancala: 6 possible moves, average depth of 40, so 6^{40} which is on the edge
 - Tic Tac Toe: branching factor of 4 (on average) and depth of 9...
 yes!

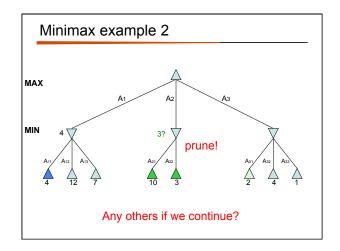
Ideas?

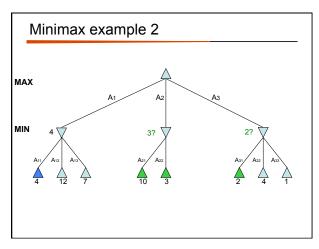
- pruning!
- improved state utility/evaluation functions

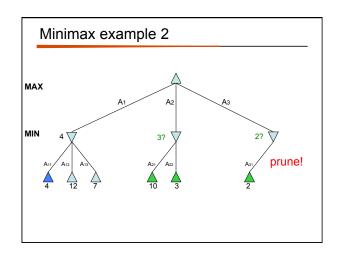












Alpha-Beta pruning

An optimal pruning strategy

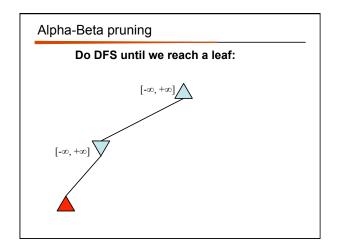
- only prunes paths that are suboptimal (i.e. wouldn't be chosen by an optimal playing player)
- returns the *same* result as minimax, but faster

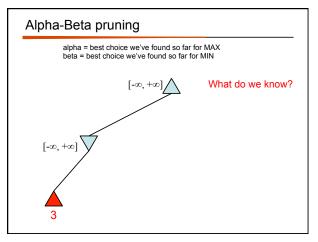
As we go, keep track of the best and worst along a path

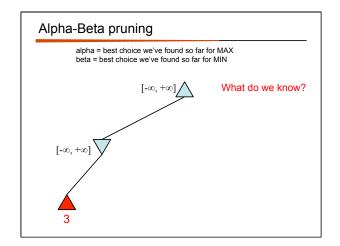
- alpha = best choice we've found so far for MAX
- beta = best choice we've found so far for MIN

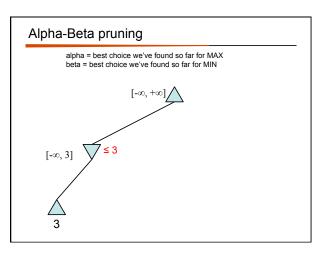
Alpha-Beta pruning alpha = best choice we've found so far for MAX Using alpha and beta to prune: - We're examining MIN's options for a ply - To do this, we're examining all possible moves for MAX. If we find a value for one of MAX's moves that is less than alpha, return. (MIN could do better down this path) MIN MAX return if any < alpha

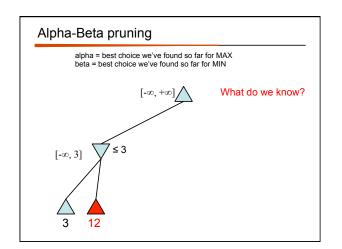
Alpha-Beta pruning beta = best choice we've found so far for MIN Using alpha and beta to prune: - We're examining MAX's options for a ply - To do this, we're examining all possible moves for MIN. If we find a value for one of MIN's possible moves that is greater than beta, return. (MIN won't end up down here) MAX MIN return if any > beta

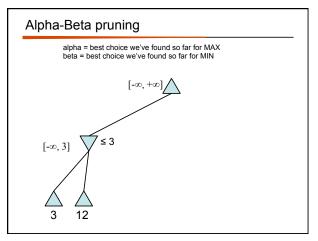


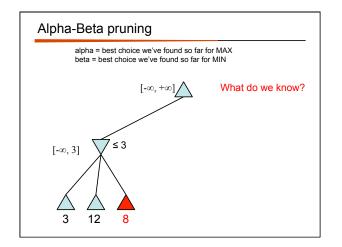


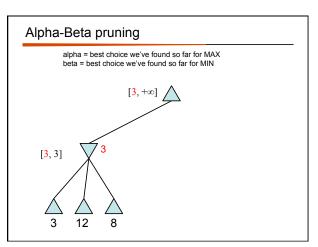


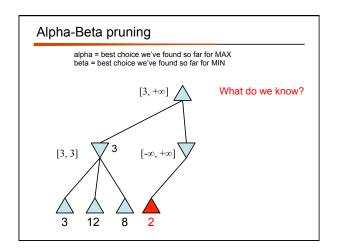


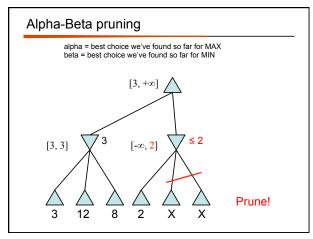


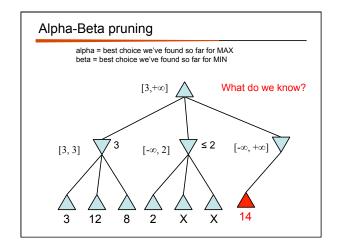


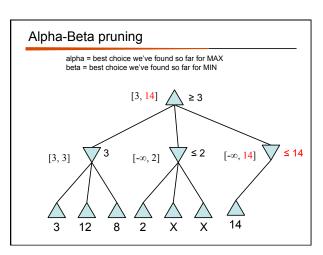


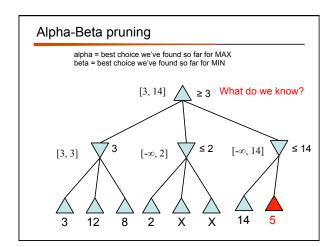


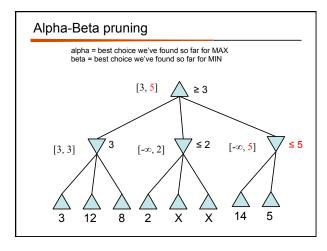


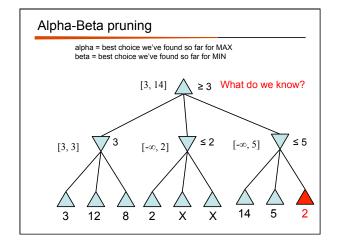


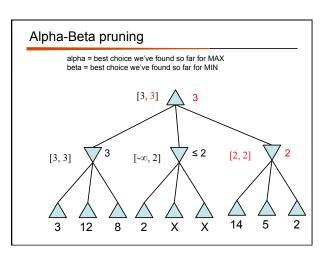












```
alpha = best choice we've found so far for MAX
                               beta = best choice we've found so far for MIN
def maxValue(state, alpha, beta):
 if state is terminal:
   return utility(state)
 else:
   value = -∞
   for all actions a in actions(state):
     value = max(value, minValue(result(state,a), alpha, beta)
     if value >= beta:
       return value # prune!
     alpha = max(alpha, value) # update alpha
    return value
 We're making a decision for MAX.
 • When considering MIN's choices, if we find a value that is greater
 than beta, stop, because MIN won't make this choice
 • if we find a better path than alpha, update alpha
```

```
alpha = best choice we've found so far for MAX
                               beta = best choice we've found so far for MIN
def minValue(state, alpha, beta):
 if state is terminal:
   return utility(state)
  else:
   value = +∞
   for all actions a in actions(state):
     value = min(value, maxValue(result(state,a), alpha, beta)
     if value <= alpha:
       return value # prune!
     beta = min(beta, value) # update alpha
    return value
   We're making a decision for MIN.
   • When considering MAX's choices, if we find a value that is less
   than alpha, stop, because MAX won't make this choice
   • if we find a better path than beta for MIN, update beta
```

Baby NIM2: take 1, 2 or 3 sticks



Effectiveness of pruning

Notice that as we gain more information about the state of things, we're more likely to prune

What affects the performance of pruning?

- key: which order we visit the states
- can try and order them so as to improve pruning

Effectiveness of pruning

If perfect state ordering:

- O(b^m) becomes O(b^{m/2})

 We can solve a tree twice as deep!

Random order:

- O(b^m) becomes O(b^{3m/4})
 still pretty good

For chess using a basic ordering

– Within a factor of 2 of $O(b^{m/2})$